

EECS 861
Homework #11

1. Under H_0 the observed signal is N and H_1 the observed signal is $4 + N$ where N is a Gaussian with zero mean and a standard deviation of 0.9.

- a. Assuming $P(H_1) = P(H_0) = 0.5$ derive the MAP decision rule.
- b. Find the P_D , P_M , and P_{fa} given the MAP decision rule. Verify your results using

Binary Detection with Gaussian Noise

- c. Find the P_e .
- d. Repeat part b. with under H_0 the observed signal is $-2 + N$ and H_1 the observed signal is $+2 + N$.

Hint: Sketch the conditional distributions for this part and part b.

2. For the parameters given in problem 1 parts a-c and the costs are given as $C_{10} = C_{01} = 2$, $C_{00} = 0$, and $C_{11} = 1$. Find the decision rule that minimizes the average cost.

3. In a target detection problem, the target is present for $0.01 \mu s$. When the target is not present only noise $N(t)$ is received. $N(t)$ is additive zero mean Gaussian WSS random process, $N(t)$ has the following PSD

$$S_N(f) = \begin{cases} \frac{\eta}{2} = 10^{-9} & |f| < 2 \text{ GHz} \\ 0 & \text{elsewhere} \end{cases}$$

When the target is present the received signal is $Y(t) = A + N(t)$ where $A = 4$. $Y(t)$ is sampled every $0.001 \mu s$. One sample of $Y(t)$ is used to detect the presence of the target.

- a. Assuming $P(\text{target is present}) = P(\text{target is not present}) = 0.5$ derive the MAP decision rule.
- b. Find P_D , P_M , and P_{fa} given the MAP decision rule.

Verify using **Binary Detection with Gaussian Noise**

- c. Design an N-P detector is to obtain a $P_{fa} = 0.01$
- d. Find P_D , P_M , and P_{fa} given the N-P detector.

4. Repeat Problem 3 part c and d using a decision variable Z where assume $T = 0.0025 \mu s$ and that you know the target is present starting at $t=0$ or not present starting at $t=0$. $Z = \frac{1}{T} \int_0^T Y(t) dt$

5. A digital signal $X(t)$ has a bit rate of 250 b/s where $X(t)$ is $-A$ V (bit=0) or $+A$ V (bit=1) and $A = 1.5$ and bits are transmitted with equal probability. T_B is the bit duration. The transmitted signal is corrupted by additive zero mean WSS random process, where $N(t)$ has the following PSD. The received signal is $Z(t) = X(t) + N(t)$. Assume the receiver is in bit synchronization.

$$S_N(f) = \begin{cases} \frac{\eta}{2} = \frac{1}{500} & |f| < 5000 \\ 0 & \text{elsewhere} \end{cases}$$

The decision variable, Y is given by $Y = \frac{1}{T_B} \int_0^{T_B} Z(t) dt$

- a. Find the distribution of $Y|0$ bit is transmitted.
- b. Find the distribution of $Y|1$ bit is transmitted.
- c. Derive the MAP decision rule.
- d. Find the probability of bit error, P_e .

Verify using **Binary Detection with Gaussian Noise**

6. Trade-offs using system specified in Problem 3 and Problem 5.

- Using system specified in Problem 3 will the P_D increase or decrease or stay the same as A increases with the N-P detector?
- Using system specified in Problem 3 will the P_{fa} increase or decrease or stay the same as A increases with the N-P detector?
- Using system specified in Problem 3 will the P_e increase or decrease as η increases in Problem 3?
- Using system specified in Problem 5 will the P_e increase or decrease or stay the same as the bit rate increases in Problem 5?

7. Under H_1 (target present) the observed signal is $A+N$ and under H_0 (target absent) the observed signal is N where N is a Gaussian with zero mean and a standard deviation of σ .

Define S/N (dB) = $10 \log(A^2 / \sigma^2)$.

On the same graph plot the ROC for $S/N = 0.5\text{dB}, 1.0\text{dB}, 3.0\text{dB}, 6\text{dB}$. Verify your answer using http://www.ittc.ku.edu/~frost/EECS_861/Mathematica_files/ROC.cdf

8. Under H_1 (target present) the observed signal has a pdf of

$$f_{Y|H_1}(y | H_1) = \frac{u(y)}{5} e^{-y/5}$$

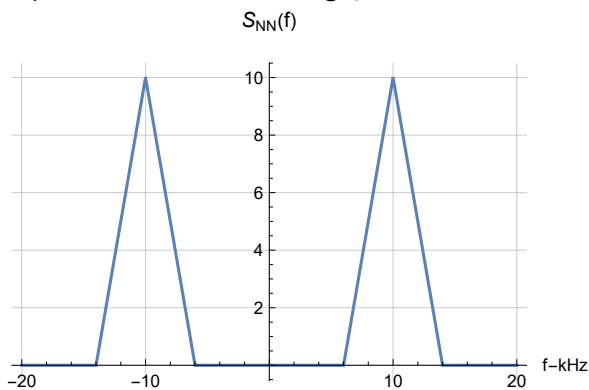
Under H_0 (target not present) the observed signal has a pdf of

$$f_{Y|H_0}(y | H_0) = \frac{u(y)}{2} e^{-y/2}$$

Two S.I. samples of the observed signal are collected. Assume $P(H_0)=0.5$.

- Derive the MAP decision rule.
- Find the pdf of the decision variable given H_0 .
- Find the pdf of the decision variable given H_1 .
- Find P_M
- Find P_{fa}

9. The spectral density of a narrowband Gaussian process $N(t)$ is shown in Below. Find the following spectral densities associated with the quadrature representation of $N(t)$ using $f_c = 10$ kHz.



- $S_{N_c N_c}(f)$
- $S_{N_c N_s}(f)$
- If f_c is changed to $f_c = 10.05$ kHz, does $S_{N_c N_c}(f)$, and $S_{N_c N_s}(f)$ change, if so why?