7-3 The Biot-Savart Law and the Magnetic Vector Potential

Reading Assignment: pp. 208-218

Q: Given some field $B(\bar{r})$, how can we determine the source $J(\bar{r})$ that created it?

A: Easy! \rightarrow $\mathbf{J}(\bar{\mathbf{r}}) = \nabla \mathbf{x} \mathbf{B}(\bar{\mathbf{r}})/\mu_0$

Q: OK, given some source $J(\overline{r})$, how can we determine what field $B(\overline{r})$ it creates?

A:

HO: The Magnetic Vector Potential

HO: Solutions to Ampere's Law

HO: The Biot-Savart Law

Example: The Uniform, Infinite Line of Current

HO: B-field from an Infinite Current Sheet

<u>The Magnetic</u> <u>Vector Potential</u>

From the magnetic form of Gauss's Law $\nabla \cdot \mathbf{B}(\overline{r}) = 0$, it is evident that the magnetic flux density $\mathbf{B}(\overline{r})$ is a solenoidal vector field.

Recall that a solenoidal field is the **curl** of some other vector field, e.g.,:

$$B(\overline{r}) = \nabla x A(\overline{r})$$

Q: The magnetic flux density $\mathbf{B}(\overline{\mathbf{r}})$ is the curl of **what** vector field ??

A: The magnetic vector potential $A(\bar{r})!$

The curl of the magnetic vector potential $\mathbf{A}(\overline{\mathbf{r}})$ is equal to the magnetic flux density $\mathbf{B}(\overline{\mathbf{r}})$:

$$\nabla \mathbf{x} \mathbf{A}(\overline{\mathbf{r}}) = \mathbf{B}(\overline{\mathbf{r}})$$

where:

magnetic vector potential $\doteq \mathbf{A}(\overline{\mathbf{r}})$

Vector field $\mathbf{A}(\overline{\mathbf{r}})$ is called the **magnetic** vector potential because of its **analogous** function to the **electric** scalar potential $V(\overline{\mathbf{r}})$.

An electric field can be determined by taking the gradient of the electric potential, just as the magnetic flux density can be determined by taking the curl of the magnetic potential:

$$\mathbf{E}(\overline{\mathbf{r}}) = -\nabla \, \mathbf{V}(\overline{\mathbf{r}}) \qquad \qquad \mathbf{B}(\overline{\mathbf{r}}) = \nabla \mathbf{x} \mathbf{A}(\overline{\mathbf{r}})$$

Yikes! We have a big problem!

There are actually (infinitely) many vector fields $\mathbf{A}(\overline{\mathbf{r}})$ whose curl will equal an arbitrary magnetic flux density $\mathbf{B}(\overline{\mathbf{r}})$. In other words, given some vector field $\mathbf{B}(\overline{\mathbf{r}})$, the solution $\mathbf{A}(\overline{\mathbf{r}})$ to the differential equation $\nabla \times \mathbf{A}(\overline{\mathbf{r}}) = \mathbf{B}(\overline{\mathbf{r}})$ is not unique !

But of course, we knew this!

To **completely** (i.e., uniquely) specify a **vector** field, we need to specify **both** its divergence and its curl.

Well, we know the **curl** of the magnetic vector potential $\mathbf{A}(\overline{\mathbf{r}})$ is equal to magnetic flux density $\mathbf{B}(\overline{\mathbf{r}})$. But, what is the **divergence** of $\mathbf{A}(\overline{\mathbf{r}})$ equal to ? I.E.,:

$$\nabla \cdot \mathbf{A}(\overline{\mathbf{r}}) = ???$$

By answering this question, we are essentially **defining** $A(\overline{r})$.

Let's define it in so that it makes our computations easier!

To accomplish this, we first start by writing **Ampere's Law** in terms of magnetic vector potential:

$$\nabla \mathbf{x} \mathbf{B}(\overline{\mathbf{r}}) = \nabla \mathbf{x} \nabla \mathbf{x} \mathbf{A}(\overline{\mathbf{r}}) = \mu_0 \mathbf{J}(\overline{\mathbf{r}})$$

We recall from **section 2-6** that:

$$abla imes
abla \nabla imes
abla oldsymbol{A}(\overline{\mathbf{r}}) =
abla (\nabla \cdot oldsymbol{A}(\overline{\mathbf{r}})) -
abla^2 oldsymbol{A}(\overline{\mathbf{r}})$$

Thus, we can **simplify** this statement if we decide that the **divergence** of the magnetic vector potential is **equal to zero**:

$$\nabla \cdot \mathbf{A}(\overline{\mathbf{r}}) = \mathbf{0}$$

We call this the gauge equation for magnetic vector potential. Note the magnetic vector potential $\mathbf{A}(\overline{r})$ is therefore also a solenoidal vector field.

$$\nabla \mathbf{x} \nabla \mathbf{x} \mathbf{A}(\overline{\mathbf{r}}) = \nabla \left(\nabla \cdot \mathbf{A}(\overline{\mathbf{r}}) \right) - \nabla^2 \mathbf{A}(\overline{\mathbf{r}})$$
$$= -\nabla^2 \mathbf{A}(\overline{\mathbf{r}})$$

And thus Ampere's Law becomes:

$$\nabla \mathbf{x} \mathbf{B}(\overline{\mathbf{r}}) = -\nabla^{2} \mathbf{A}(\overline{\mathbf{r}}) = \mu_{0} \mathbf{J}(\overline{\mathbf{r}})$$

Note the Laplacian operator ∇^2 is the vector Laplacian, as it operates on vector field $\mathbf{A}(\overline{\mathbf{r}})$.

Summarizing, we find the magnetostatic equations in terms of magnetic vector potential $A(\overline{r})$ are:

$$\nabla \mathbf{x} \mathbf{A}(\overline{\mathbf{r}}) = \mathbf{B}(\overline{\mathbf{r}})$$
$$\nabla^2 \mathbf{A}(\overline{\mathbf{r}}) = -\mu_0 \mathbf{J}(\overline{\mathbf{r}})$$
$$\nabla \cdot \mathbf{A}(\overline{\mathbf{r}}) = \mathbf{0}$$

Note that the **magnetic** form of Gauss's equation results in the equation $\nabla \cdot \nabla \times \mathbf{A}(\mathbf{\bar{r}}) = 0$. Why don't we include this equation in the above list?

Compare the magnetostatic equations using the magnetic vector potential $\mathbf{A}(\mathbf{\bar{r}})$ to the electrostatic equations using the electric scalar potential $V(\bar{r})$:

$$\mathbf{E}(\overline{\mathbf{r}}) = -\nabla \, \mathbf{V}(\overline{\mathbf{r}})$$

$$\nabla \cdot \mathbf{E}(\overline{\mathbf{r}}) = \frac{\rho_{\nu}(\overline{\mathbf{r}})}{\varepsilon_{0}}$$

Hopefully, you see that the two potentials $\mathbf{A}(\overline{\mathbf{r}})$ and $V(\overline{\mathbf{r}})$ are in many ways analogous.

For example, we know that we can determine a static field $\mathbf{E}(\bar{\mathbf{r}})$ created by sources $\rho_{\nu}(\bar{r})$ either **directly** (from Coulomb's Law), or indirectly by first finding potential $V(\bar{r})$ and then taking its derivative (i.e., $\mathbf{E}(\overline{r}) = -\nabla V(\overline{r})$).

Likewise, the magnetostatic equations above say that we can determine a static field $B(\overline{r})$ created by sources $J(\overline{r})$ either directly, or indirectly by first finding potential $A(\bar{r})$ and then taking its derivative (i.e., $\nabla \times \mathbf{A}(\overline{\mathbf{r}}) = \mathbf{B}(\overline{\mathbf{r}})$).

 $\begin{array}{ccc} \rho_{\nu}(\bar{r}) & \Rightarrow & \mathcal{V}(\bar{r}) & \Rightarrow & \mathsf{E}(\bar{r}) \\ & & & & \\ \mathbf{J}(\bar{r}) & \Rightarrow & \mathbf{A}(\bar{r}) & \Rightarrow & \mathsf{B}(\bar{r}) \end{array}$

Solutions to Ampere's Law

Say we know the current distribution $J(\bar{r})$ occurring in some physical problem, and we wish to find the resulting magnetic flux density $B(\bar{r})$.

Q: How do we find $B(\overline{r})$ given $J(\overline{r})$?

A: Two ways! We either directly solve the differential equation:

 $\nabla \mathbf{x} \mathbf{B}(\overline{\mathbf{r}}) = \mu_0 \mathbf{J}(\overline{\mathbf{r}})$

Or we first solve this differential equation for vector field $\mathbf{A}(\overline{\mathbf{r}})$:

$$-\nabla^{2}\boldsymbol{A}(\bar{\boldsymbol{r}}) = \mu_{0}\boldsymbol{J}(\bar{\boldsymbol{r}})$$

and then find $B(\overline{r})$ by taking the curl of $A(\overline{r})$ (i.e., $\nabla \times A(\overline{r}) = B(\overline{r})$).

It turns out that the **second** option is often the easiest!

To see why, consider the vector Laplacian operator if vector field $\mathbf{A}(\overline{r})$ is expressed using Cartesian base vectors:

$$\nabla^{2}\boldsymbol{A}(\overline{\boldsymbol{r}}) = \nabla^{2}\boldsymbol{A}_{x}(\overline{\boldsymbol{r}})\,\hat{\boldsymbol{a}}_{x} + \nabla^{2}\boldsymbol{A}_{y}(\overline{\boldsymbol{r}})\,\hat{\boldsymbol{a}}_{y} + \nabla^{2}\boldsymbol{A}_{z}(\overline{\boldsymbol{r}})\,\hat{\boldsymbol{a}}_{z}$$

We therefore write **Ampere's Law** in terms of **three** separate **scalar** differential equations:

$$\nabla^{2}\mathcal{A}_{x}\left(\overline{\mathbf{r}}\right) = -\mu_{0}\mathcal{J}_{x}\left(\overline{\mathbf{r}}\right)$$

$$\nabla^{2}\mathcal{A}_{\mathcal{Y}}(\overline{\mathbf{r}}) = -\mu_{0}\mathcal{J}_{\mathcal{Y}}(\overline{\mathbf{r}})$$

$$\nabla^{2}\mathcal{A}_{z}\left(\overline{\mathbf{r}}\right)=-\mu_{0}\mathcal{J}_{z}\left(\overline{\mathbf{r}}\right)$$

Each of these differential equations is **easily solved**. In fact, we **already know** their solution!

Recall we had the **exact** same differential equation in electrostatcs (i.e., Poisson's equation):

$$\nabla^{2} \mathcal{V}(\overline{\mathbf{r}}) = \frac{-\rho_{v}(\overline{\mathbf{r}})}{\varepsilon_{0}}$$

We know the solution $V(\overline{r})$ to this differential equation is:

$$V(\overline{\mathbf{r}}) = \frac{1}{4\pi \,\varepsilon_0} \iiint \frac{\rho_v(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} \, dv'$$

Mathematically, Poisson's equation is **exactly** the same as **each** of the three scalar differential equations at the top of the page, with these **substitutions**:

$$\mathcal{V}(\bar{\mathbf{r}}) \to \mathcal{A}_{\mathbf{x}}(\bar{\mathbf{r}}) \qquad \rho_{\mathbf{v}}(\bar{\mathbf{r}}) \to \mathbf{J}_{\mathbf{x}}(\bar{\mathbf{r}}) \qquad \frac{\mathbf{I}}{\mathbf{\epsilon}_{\mathbf{v}}} \to \mu_{\mathbf{0}}$$

The **solutions** to the **magnetic** differential equation are therefore:

$$\mathcal{A}_{x}\left(\overline{\mathbf{r}}\right) = \frac{\mu_{0}}{4\pi} \iiint_{\nu} \frac{\mathcal{J}_{x}\left(\overline{\mathbf{r}}'\right)}{\left|\overline{\mathbf{r}} - \overline{\mathbf{r}}'\right|} d\nu'$$

$$\mathcal{A}_{\mathcal{Y}}(\overline{\mathbf{r}}) = \frac{\mu_{0}}{4\pi} \iiint_{\mathcal{V}} \frac{\mathcal{J}_{\mathcal{Y}}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} d\mathbf{v}'$$

$$\mathcal{A}_{z}\left(\overline{\mathbf{r}}\right) = \frac{\mu_{0}}{4\pi} \iiint_{v} \frac{\mathcal{J}_{z}\left(\overline{\mathbf{r}}'\right)}{\left|\overline{\mathbf{r}}-\overline{\mathbf{r}}'\right|} dv'$$

and since:

$$\mathbf{A}(\overline{\mathbf{r}}) = \mathbf{A}_{x}(\overline{\mathbf{r}}) \ \hat{a}_{x} + \mathbf{A}_{y}(\overline{\mathbf{r}}) \ \hat{a}_{y} + \mathbf{A}_{z}(\overline{\mathbf{r}}) \ \hat{a}_{z}$$

and:

$$\mathbf{J}(\overline{\mathbf{r}}) = J_{x}(\overline{\mathbf{r}}) \ \hat{a}_{x} + J_{y}(\overline{\mathbf{r}}) \ \hat{a}_{y} + J_{z}(\overline{\mathbf{r}}) \ \hat{a}_{z}$$

we can **combine** these three solutions and get the **vector** solution to our **vector** differential equation:

$$\mathbf{A}(\overline{\mathbf{r}}) = \frac{\mu_0}{4\pi} \iiint_{\mathbf{v}} \frac{\mathbf{J}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} \, d\mathbf{v}'$$

Therefore, given current distribution $\mathbf{J}(\overline{\mathbf{r}})$, we use the above equation to determine magnetic vector potential $\mathbf{A}(\overline{\mathbf{r}})$. We then take the curl of this result to determine magnetic flux density $\mathbf{B}(\overline{\mathbf{r}})$.

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For surface current, the resulting magnetic vector potential is:

$$\mathbf{A}(\overline{\mathbf{r}}) = \frac{\mu_0}{4\pi} \iint_{\mathcal{S}} \frac{\mathbf{J}_{\mathcal{S}}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} d\mathcal{S}'$$

and for a current I flowing along contour C, we find:

$$\mathbf{A}(\overline{\mathbf{r}}) = \frac{\mu_0 \ \mathbf{I}}{4\pi} \oint_{\mathcal{C}} \frac{\overline{d\ell'}}{|\overline{\mathbf{r}} - \overline{\mathbf{r}'}|}$$

Again, ponder the **analogy** between these equations involving sources and potentials and the equivalent equation from electrostatics:

$$V(\overline{r}) = \frac{1}{4\pi \epsilon_0} \iiint_{\nu} \frac{\rho_{\nu}(\overline{r}')}{|\overline{r} - \overline{r}'|} d\nu'$$

The Biot-Savart Law

So, we now know that given some current density, we can find the resulting magnetic vector potential $A(\overline{r})$:

$$\mathbf{A}(\mathbf{\overline{r}}) = \frac{\mu_0}{4\pi} \iiint_{\mathbf{V}} \frac{\mathbf{J}(\mathbf{\overline{r'}})}{|\mathbf{\overline{r}} - \mathbf{\overline{r'}}|} d\mathbf{v'}$$

and then determine the resulting magnetic flux density $B(\overline{r})$ by taking the curl: $B(\overline{r}) = \nabla \times A(\overline{r})$

Q: Golly, can't we somehow combine the curl operation and the magnetic vector potential integral?

A: Yes! The result is known as the **Biot-Savart Law**.

Combining the two above equations, we get:

$$\mathbf{B}(\overline{\mathbf{r}}) = \nabla \mathbf{x} \frac{\mu_0}{4\pi} \iiint \frac{\mathbf{J}(\overline{\mathbf{r}'})}{|\overline{\mathbf{r}} - \overline{\mathbf{r}'}|} d\mathbf{v}'$$

This result is of course **not** very helpful, but we note that we can move the curl operation **into** the integrand:

$$\mathbf{B}(\overline{\mathbf{r}}) = \frac{\mu_{0}}{4\pi} \iiint_{\mathbf{v}} \nabla \mathbf{x} \frac{\mathbf{J}(\overline{\mathbf{r}}')}{|\overline{\mathbf{r}} - \overline{\mathbf{r}}'|} d\mathbf{v}'$$

Note this result **reverses** the process: **first** we perform the curl, and **then** we integrate.

We can do this is because the **integral** is over the **primed** coordinates (i.e., \overline{r}) that specify the **sources** (current density), while the **curl** take the derivatives of the **unprimed** coordinates (i.e., \overline{r}) that describe the **fields** (magnetic flux density).

Q: Yikes! That curl operation still looks particularly **difficult**. How we perform it?

A: We take advantage of a know vector identity! The curl of vector field $f(\bar{r})G(\bar{r})$, where $f(\bar{r})$ is any scalar field and $G(\bar{r})$ is any vector field, can be evaluated as:

$$\nabla \mathsf{x}(\mathsf{f}(\overline{\mathsf{r}})\mathsf{G}(\overline{\mathsf{r}})) = f(\overline{\mathsf{r}})\nabla \mathsf{x}\mathsf{G}(\overline{\mathsf{r}}) - \mathsf{G}(\overline{\mathsf{r}})\mathsf{x}\nabla f(\overline{\mathsf{r}})$$

Note the integrand of the above equation is in the form $\nabla x(f(\overline{r})G(\overline{r}))$, where:

$$f(\overline{r}) = \frac{1}{|\overline{r} - \overline{r'}|}$$
 and $G(\overline{r}) = J(\overline{r'})$

Therefore we find:

$$\nabla \times \left(\frac{\mathbf{J}\left(\vec{r}' \right)}{\left| \vec{r} - \vec{r}' \right|} \right) = \frac{1}{\left| \vec{r} - \vec{r}' \right|} \nabla \times \mathbf{J}\left(\vec{r}' \right) - \mathbf{J}\left(\vec{r}' \right) \times \nabla \left(\frac{1}{\left| \vec{r} - \vec{r}' \right|} \right)$$

In the **first** term we take the **curl** of $\mathbf{J}(\vec{r'})$. Note however that this vector field is a **constant** with respect to the **unprimed** coordinates \vec{r} . Thus the **derivatives** in the curl will all be equal to **zero**, and we find that:

$$\nabla \mathbf{x} \mathbf{J}(\mathbf{r}') = \mathbf{0}$$

Likewise, it can be shown that:

$$\left(\frac{1}{\left|\overline{\mathbf{r}}-\overline{\mathbf{r}}'\right|}\right) = -\frac{\overline{\mathbf{r}}-\overline{\mathbf{r}}'}{\left|\overline{\mathbf{r}}-\overline{\mathbf{r}}'\right|^{3}}$$

Using these results, we find:

$$\nabla \mathbf{x} \left(\frac{\mathbf{J}(\mathbf{\bar{r}}')}{|\mathbf{\bar{r}} - \mathbf{\bar{r}}'|} \right) = \frac{\mathbf{J}(\mathbf{\bar{r}}') \mathbf{x}(\mathbf{\bar{r}} - \mathbf{\bar{r}}')}{|\mathbf{\bar{r}} - \mathbf{\bar{r}}'|^3}$$

and therefore the magnetic flux density is:

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$$\mathbf{B}(\overline{\mathbf{r}}) = \frac{\mu_{0}}{4\pi} \iiint_{\nu} \frac{\mathbf{J}(\overline{\mathbf{r}}') \mathbf{x}(\overline{\mathbf{r}} - \overline{\mathbf{r}}')}{\left|\overline{\mathbf{r}} - \overline{\mathbf{r}}'\right|^{3}} d\nu'$$

This is know as the Biot-Savart Law !

is:

For a surface current $\mathbf{J}_{s}(\overline{\mathbf{r}})$, the Biot-Savart Law becomes:

$$\mathbf{B}(\overline{\mathbf{r}}) = \frac{\mu_{0}}{4\pi} \iint_{S} \frac{\mathbf{J}_{s}(\overline{\mathbf{r}}') \mathbf{x}(\overline{\mathbf{r}} - \overline{\mathbf{r}}')}{\left|\overline{\mathbf{r}} - \overline{\mathbf{r}}'\right|^{3}} ds'$$

and for line current I, flowing on contour C, the Biot-Savart Law

$$\mathbf{B}(\overline{\mathbf{r}}) = \frac{\mu_0 \mathbf{I}}{4\pi} \oint_{\mathcal{C}} \frac{\overline{d\ell'} \mathbf{x} (\overline{\mathbf{r}} - \overline{\mathbf{r}'})}{|\overline{\mathbf{r}} - \overline{\mathbf{r}'}|^3}$$

Note the contour C is closed. Do you know why?



Note that the Biot-Savart Law is therefore **analogous** to **Coloumb's Law** in Electrostatics (Do you see why?)!

<u>Example: The Uniform.</u> Infinite Line of Current

Consider electric current I flowing along the *z*-axis from $z = -\infty$ to $z = \infty$. What magnetic flux potential $B(\bar{r})$ is created by this current?



We can determine the magnetic flux density by applying the **Biot-Savart Law**:

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$$\mathbf{B}(\mathbf{\bar{r}}) = \frac{\mu_0 I}{4\pi} \oint_{\mathcal{C}} \frac{\overline{d\ell'} \times (\mathbf{\bar{r}} - \mathbf{\bar{r}'})}{|\mathbf{\bar{r}} - \mathbf{\bar{r}'}|^3}$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{\hat{a}_z \times \left[\rho \cos\phi \,\hat{a}_x + \rho \sin\phi \,\hat{a}_y + (z - z') \,\hat{a}_z\right]}{\left[\rho^2 + (z - z')^2\right]^{3/2}} dz'$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{\rho \cos\phi \,\hat{a}_y - \rho \sin\phi \,\hat{a}_x}{\left[\rho^2 + (z - z')^2\right]^{3/2}} dz'$$

$$= \frac{\mu_0 I}{4\pi} \left(\rho \cos\phi \,\hat{a}_y - \rho \sin\phi \,\hat{a}_x\right) \int_{-\infty}^{\infty} \frac{du}{\left[\rho^2 + u^2\right]^{3/2}}$$

$$= \frac{\mu_0 I}{4\pi} \left(\rho \,\hat{a}_\phi\right) \Big|_{-\infty}^{\infty} \frac{\mathbf{u}}{\rho^2 \sqrt{\rho^2 + u^2}}$$

$$= \frac{\mu_0 I}{4\pi} \left(\rho \,\hat{a}_\phi\right) \frac{2}{\rho^2}$$

Therefore, the magnetic flux density **created** by a "wire" with current *I* flowing along the *z*-axis is:

$$\mathbf{B}(\overline{\mathbf{r}}) = \frac{\mu_0 \ \mathbf{I}}{2\pi \ \rho} \, \hat{\mathbf{a}}_{\phi}$$

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Think about what this expression tells us about magnetic flux density:

- * The magnitude of $\mathbf{B}(\overline{\mathbf{r}})$ is proportional to $1/\rho$, therefore magnetic flux density **diminishes** as we move farther from "wire".
- * The direction of $\mathbf{B}(\overline{\mathbf{r}})$ is \hat{a}_{ϕ} . In other words, the magnetic flux density points in the direction **around** the wire.



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<u>B-Field from an Infinite</u> <u>Sheet of Current</u>

Consider now an **infinite sheet** of current, lying on the z = 0 plane. Say the surface current density on this sheet has a value:

$$\mathbf{J}_{s}\left(\overline{\mathbf{r}}\right)=J_{x}\,\hat{a}_{x}$$

meaning that the current density at every point on the surface has the same magnitude, and flows in the \hat{a}_x direction.

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Using the Biot-Savart Law, we find that the magnetic flux density produced by this **infinite** current sheet is:

 $J_x \hat{a}_x$

$$\mathbf{B}(\mathbf{\bar{r}}) = \begin{cases} -\frac{\mu_0 J_x}{2} \, \hat{a}_y \, \mathbf{z} > 0 \\ \\ \frac{\mu_0 J_x}{2} \, \hat{a}_y \, \mathbf{z} < 0 \end{cases}$$

Think about what this expression is telling us.

* The magnitude of this magnetic flux density is a **constant**. In other words, $\mathbf{B}(\overline{r})$ is **just** as large a million miles from the infinite current sheet as it is 1 millimeter from the current sheet!

* The direction of the magnetic flux density in the $-\hat{a}_{y}$ direction above the current sheet, but points in the opposite direction (i.e., \hat{a}_{y}) below it.

* The direction of the magnetic flux density is **orthogonal** to the direction of current flow \hat{a}_x .

Plotting the vector field $\mathbf{B}(\overline{\mathbf{r}})$ along the y-z plane, we find:

