## <u>AGC</u>

To implement **Automatic Gain Control** (AGC) we need to make the gain of the IF amplifier **adjustable**:



## Q: Are there such things as adjustable gain amplifiers?

## A: Yes and no.

Typically, voltage controlled amplifiers work **poorly**, have **limited** gain adjustment, or **both**.

Instead, receiver designers implement an adjustable gain amplifier using one or more **fixed gain amplifiers** and one or more **variable attenuators** (e.g., digital attenuators).



Two amplifiers are used in the design above, although one, two, three, or even four amplifiers are sometimes used.

The adjustable **attenuator** can likewise be implemented in a number of ways. Recall the attenuator can be either **digital** or **voltage controlled**. Likewise, the attenuator can be implemented using either **one** attenuator, or with **multiple** cascaded attenuator components.

However it is implemented, the **gain** of the overall IF amplifier is simply the **product** of the fixed amplifier gains, **divided** the total attenuation *A*. Thus, for the example above:

$$G^{IF} = \frac{G_1 G_2}{A}$$

Now, the key point here is that this gain is **adjustable**, since the attenuation can be varied from:

$$A_L < A < A_H$$

Thus, the IF amplifier gain can **vary** from:

$$\mathcal{G}_{L}^{IF} < \mathcal{G} < \mathcal{G}_{H}^{IF}$$

Where  $G_{L}^{IF}$  is the **lowest** possible IF amplifier gain:

$$G_{L}^{IF} = \frac{G_{1}G_{2}}{A_{H}}$$

And  $G_{H}^{IF}$  is the **highest** possible IF amplifier gain:

$$G_{\mathcal{H}}^{IF} = rac{G_1 G_2}{A_1}$$

Note the gain is the highest when the attenuation is the lowest, and vice versa (this should make perfect sense to you!).

However, recall that the value of the **lowest attenuation** value is **not equal to one** (i.e.,  $A_2 > 1$ ). Instead  $A_2$  represents the **insertion loss** of the attenuators when in their minimum attenuation state.

Recall also that the **total receiver gain** is the product of the gains of **all** the components in the receiver chain. For example:

 $G = G_{LNA}G_{preselector}G_{mixer}G^{IF}G_{IFfilter}$ 

Note, however, that the only **adjustable** gain in this chain is the **IF** amplifier gain  $G^{IF}$ , thus the remainder of the receiver gain is **fixed**, and we can thus define this **fixed** gain  $G_{fixed}$  as:

$$G_{fixed} = \frac{G}{G^{IF}}$$

Thus,  $G_{fixed}$  is simply the gain of the entire receiver, with the **exception** of the IF amplifier.

Since the gain of the **IF amplifier** is adjustable, the gain of **entire receiver** is likewise adjustable, varying over:

$$G_L < G < G_H$$

where:

$$G_L = G_{fixed} G_L^{IF}$$

and:

$$\mathcal{G}_{\mathcal{H}}=\mathcal{G}_{\mathit{fixed}}\;\mathcal{G}_{\mathcal{H}}^{\mathit{IF}}$$

Thus, a receiver designer must design the "IF Amplifier" such that the **largest possible** receiver gain  $G_H$  exceeds the minimum gain requirement (i.e.,  $G_H > G_{min}$ )—a requirement that is applicable when the receiver input signal is at its smallest (i.e., when  $P_{in} = MDS$ ).

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To accomplish this, we find that:

$$\begin{array}{c} G_{H} > G_{min} \\ G_{fixed} G_{H}^{IF} > G_{min} \\ G_{H}^{IF} > \frac{G_{min}}{G_{fixed}} \end{array}$$

Thus, since  $G_{min} = P_D^{min} / MDS$  we can conclude that the **highest** possible gain  $G_H^{IF}$  of our "IF amplifier" **must** exceed:

$$G_{H}^{IF} > rac{P_{D}^{min}}{G_{fixed} MDS}$$

or

$$\mathcal{G}_{\mathcal{H}}^{IF}\left(dB
ight) > \mathcal{P}_{\mathcal{D}}^{min}\left(dBm
ight) - \mathcal{G}_{fixed}\left(dB
ight) - MDS\left(dBm
ight)$$

Additionally, a receiver designer must design the "IF Amplifier" such that the **smallest possible** receiver gain  $G_L$  is **less** that the maximum gain requirement (i.e.,  $G_L < G_{max}$ )—a requirement that is applicable when the receiver input signal is at its **largest** (i.e., when  $P_{in} = P_{in}^{sat}$ ).

To accomplish this, we find that:



Thus, since  $G_{max} = P_D^{max} / P_{in}^{sat}$  we can conclude that the **lowest possible** gain  $G_L^{IF}$  of our "IF amplifier" must be **lower** than:

$$\mathcal{G}_{L}^{IF} < rac{\mathcal{P}_{D}^{max}}{\mathcal{G}_{fixed} \ \mathcal{P}_{in}^{sat}}$$

or

$$\mathcal{G}_{L}^{IF}\left(d\mathcal{B}\right) < \mathcal{P}_{D}^{max}\left(d\mathcal{B}m\right) - \mathcal{G}_{fixed}\left(d\mathcal{B}\right) - \mathcal{P}_{in}^{sat}\left(d\mathcal{B}m\right)$$

**Q**: I'm still a bit confused. Now what is the **difference** between  $G_{min}$ ,  $G_{max}$  and  $G_L$ ,  $G_H$ ?

A: The values  $G_{min}$  and  $G_{max}$  are in fact **requirements** that are placed on the receiver designer. There **must** be some IF gain setting that will result in a receiver gain greater than  $G_{min}$ , and there **must** be some IF gain setting that will result in a receiver gain less than  $G_{max}$ .

In contrast, the values  $G_L$  and  $G_H$  are the **actual** minimum and maximum values of the receiver gain. They state the performance of a **specific receiver design**.

Properly designed, we will find that  $G_H > G_{min}$ , and  $G_L < G_{max}$ . However, this is true **only** if we have properly design our "IF Amplifier"!